

# Practical introduction to GRASS and related software for beginners

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# Who are you, anyway?

We are researchers in GIS and environmental applications at the University of Trento, Italy, for more than ten years.

We have organized the "Open Source Free Software GIS - GRASS users conference 2002", Trento, Italy, in 2002.

We have already organized the workshops:

- "GRASS Beginners" and "GRASS external RDBMS" for FOSS4G2006
- "GRASS GIS and RDBMS" for FOSS4G2007
- "Practical introduction to GRASS and related software for beginners" for FOSS4G2008



# What are we going to do?

Well, of course, a “Practical introduction to GRASS and related software for beginners”!

It consists in:

- ✓ a brief presentation of GRASS;
- ✓ a hands-on tutorial.



# What are we going to use?

The workshop material is self-contained in the live DVD we are using. The DVD contains:

- ✓ The software
  - ✓ Kubuntu 9.04 live with:
    - ✓ GRASS GIS 6.4RC4;
    - ✓ R 2.9.0 with GRASS support;
    - ✓ QGIS 1.10 with GRASS plugin, PostgreSQL 8.3.7, PostGIS 1.3.3, pgAdminIII 1.8.4 and pgagent 1.8.4.
  - ✓ GRASS tutorial;
  - ✓ These slides.

The DVD can be used live or as an installer.



# Where can I find this?

The workshop material is available on our web site:

<http://www.ing.unitn.it/~grass>

There you find:

- ✓ The LIVE DVD iso image;
- ✓ GRASS tutorials;
- ✓ Other GRASS and GIS related documents and software.

At the end of the workshop you can take the DVD home with you.



# What is GRASS?

**grass** [gras, grahs] noun

1. any plant of the family Gramineae, having jointed stems, sheathing leaves, and seedlike grains...
2. GRASS GIS (**G**eographic **R**esources **A**nalysis **S**upport **S**ystem), a Geographic Information System (GIS).  
It is available under the GNU General Public License (GPL).  
It is part of the OSGeo's projects family.



# Where does GRASS come from?

GRASS was originally developed in the beginning of the 1980s by the US Army Construction Engineering Research Laboratories (USA-CERL), published as a public domain software.

The USA-CERL withdrew from the GRASS development in the early 1990s.

From 1999 it is developed by an international developer team, which published GRASS as a free software under the terms of the GNU General Public License.

The main site is <http://grass.osgeo.org/>



# What can GRASS do for me?

Main GRASS features are:

- 2D raster analysis and 3D voxel (volumes) management
- 2D/3D vector engine with SQL based DBMS support
- Image processing modules
- Vector network analysis, Linear Referencing System
- Visualization of 2D, 3D maps and volumes
- Interoperable with standard raster and vector formats
- Works on GNU/Linux, Mac OS X, MS-Windows and other POSIX compliant platforms
- Modular architecture and scripting capabilities for batch processing







# Is GRASS alone out there?

GRASS can be used as a stand alone Desktop GIS and as the backbone of a complete GIS infrastructure:

## Data viewer GIS Analysis DBMS

QGIS	GRASS	PostgreSQL/PostGIS
Thuban	GRASS/R-stats	MySQL
OpenEV	JGRASS	
	JUMP	
	uDIG	
	gvSIG	

## Web Mapping Interoperability

UMLN Mapserver	GDAL/OGR
GeoServer	PROJ4
Mapbender	FDO
Mapbuilder	GeoTools
Openlayers	GEOS



JUMP Unified Mapping Platform



# Where can I get GRASS?



The screenshot shows the GRASS GIS website homepage. At the top, there is a navigation menu with links for Home, Intro, Docs, Download, Community, Applications, and Development. The main heading is "Welcome to GRASS GIS" with a sub-message: "You are at the official GRASS site in UNITED STATES (US) (mirror sites). This site is updated daily: 11 Sep 2009". Below this is a "Celebrating 25 years!" banner featuring a world map and the text "GRASS User map (without pop-up)". The main content area is titled "Geographic Resources Analysis Support System" and describes GRASS as free GIS software used for geospatial data management, analysis, and visualization. A "Module of the day" section highlights the `r.le.patch` module. A "Latest News!" section lists recent updates, including the release of GRASS 6.4.0 RC5 and a new WinGrass stand-alone package. A sidebar on the left contains a search bar, a "Donate" button, and various links like "About GRASS", "Screenshots", "Download", "Wiki - help site | FAQ", "Mirror sites", "Mailing lists | IRC", "Translating", "Newsletter", "Get involved!", "GRASS in the Press", and "Bug/Feature trackers".

The main reference is  
the web site

<http://grass.osgeo.org/>



# Which versions of GRASS exist?

File Edit View History Bookmarks Tools Help

http://grass.osgeo.org/download/index.php

Most Visited R Repubblica ./. BBC NEWS lAdige MeteoTrentino DOLOMITI METEO ESSE3 Router

[ GRASS: [Older versions](#) | [6.4.x stable](#) | [7.x unstable](#) ]

**GRASS 6.4.x (next stable version; new wxPython GUI, [more...](#))**  
Currently undergoing final testing.

	Binaries	Source code	Manuals
NEXT STABLE	<ul style="list-style-type: none"> <li>GNU/Linux:               <ul style="list-style-type: none"> <li>Debian</li> <li>Mandriva 2009.1 (urpmi grass)</li> <li>OpenSUSE (Geo Repo)</li> <li>Ubuntu (9.04, 9.10)</li> </ul> </li> <li>MacOSX</li> <li>MS-Windows</li> </ul>	<ul style="list-style-type: none"> <li><a href="#">grass-6.4.0RC5.tar.gz (grass-6.4.0RC5.md5sum)</a></li> <li><a href="#">Weekly 6.4-svn snapshot</a></li> <li><a href="#">Download latest 6.4-svn code</a></li> <li><a href="#">6.4-svn source code browser</a></li> </ul>	<ul style="list-style-type: none"> <li><a href="#">User manual pages</a></li> <li><a href="#">Programmer's Manual</a></li> <li><a href="#">Compiling source code</a></li> </ul>
	Weekly snapshot: <ul style="list-style-type: none"> <li>Generic GNU/Linux</li> </ul>		

**GRASS 6.5 (restricted development; testbed for backporting, [more...](#))**  
Utility version for developers, only available [as source code](#).

**GRASS 7 (active development version; partial rewrite, [more...](#))**  
Unstable, but usually works. Compatibility with earlier versions is not guaranteed.

	Binaries	Source code	Manuals
NEW DEVELOP	Weekly snapshot: <ul style="list-style-type: none"> <li>Generic GNU/Linux</li> </ul>	<ul style="list-style-type: none"> <li><a href="#">Weekly 7.0-svn snapshot</a></li> <li><a href="#">Download latest 7.0-svn code</a></li> <li><a href="#">7.0-svn source code browser</a></li> </ul>	<ul style="list-style-type: none"> <li><a href="#">User manual pages</a></li> <li><a href="#">Programmer's Manual</a></li> <li><a href="#">Compiling source code</a></li> </ul>

Download from GRASS SVN repository

Done

- 3 GRASS versions are currently available:
- 6.4.0 RC5 (next) stable
  - 6.5 development
  - 7 development (rewrite)



# Which OSs does GRASS run on?

GRASS is developed mostly in Linux but binaries for other operative systems are available (besides source code as weekly snapshot or SVN):

**6.4.0** (next) stable: GNU/Linux (Generic weekly snapshot, Debian, Mandriva, OpenSUSE, Ubuntu), MacOSX, MS Windows (Windows XP and Vista, 32 and 64 bit).

**6.5** development: source code only.

**7** development (rewrite): GNU/Linux (Generic), source code.



# Binary or source code?

Should I compile GRASS?

There are pros and cons:

	Pros	Cons
Binary	Easy and fast installation	Standard compile parameters, generated periodically
Source	Optimization possible, latest version available	Must be configured, development libraries must be available

For beginners binaries are the best choice, those able to configure and compile GRASS from source benefit from its optimization (and the possibility to develop).



# What if I want only to try GRASS?

The easiest way to try out GRASS without messing with installation is to use a Live CD/DVD or an USB distribution with pre-installed GRASS.

See <http://grass.osgeo.org/download/cdrom.php>

**USB stick:** slaxGIS, FOSSGIS on USB Stick.

**CDROM/DVD:** ArcheOS, DebianGIS Live Image, FOSS4G Toolkit CD, FOSS4G2006 LiveCD, FOSS4G2008 live Workshop DVD, geobuntu, , GISAK - Knoppix based GIS LiveCD, Italian GRASS DVD, Ominiverdi LiveCD Project, OSGEO Live GIS Disc, Poseidon Linux, SOURCEPOLE GIS Knoppix.







# What does GRASS look like?

GNU/Linux (KDE 4)

The screenshot displays the GRASS GIS desktop environment. On the left, the 'GRASS GIS Layer Manager' window shows two display panes, 'Display 1' and 'Display 2', both containing the layers 'streams@PERMANENT' and 'elevation@PERMANENT' at 100% opacity. Below this is a 'Map layers for each display' section and a command prompt.

In the center, the 'g.region [general]' dialog box is open, showing options to set the geographic region. It includes tabs for 'Existing', 'Bounds', 'Resolution', 'Effects', and 'Print'. Under the 'Existing' tab, there are several input fields for setting the region based on existing maps or files, along with checkboxes for 'Set from default region' and 'Save as default region'. Buttons for 'Close', 'Stop', 'Run', 'Copy', and 'Help' are at the bottom.

On the right, the 'GRASS GIS Map Display' window shows a 2D map view of a terrain with stream networks overlaid. The terrain is color-coded by elevation, with higher elevations in yellow and orange, and lower elevations in green and blue. The stream network is shown in dark blue. The window includes a toolbar with navigation tools and a '3D view' dropdown menu.

At the bottom left, a terminal window titled 'paolo : grass64' shows the GRASS logo and a welcome message for version 6.4.0RC4 (2009). The terminal text includes the GRASS homepage URL, instructions on how to run commands as administrator, and the current prompt: 'GRASS 6.4.0RC4 (gisdemo\_ncspm):~ > |'.

See also <http://grass.osgeo.org/screenshots/index.php>



# How many GUIs exist?

Short answer: a lot.

Long answer: one of the best features of GRASS is that everything can be done using the **C**ommand **L**ine **I**nterface (CLI), the GUIs “build” the command line. Historically, several interfaces have been developed. Those actually in use are:

**Python:** the current interface for 6.4;

**Tcl/Tk:** it is used in older versions, up to 6.3 (but it is still available in the current version, you can try it with “g.gui gui=tcltk” or “g.gui gui=oldtcltk”);

**QGIS:** this GIS can be used as an interface for GRASS, since it is able to run GRASS commands. This approach is mostly used in MS Windows.





# What do I need to run GRASS?

A fairly modern Pc will do.

You need an operative system supported by GRASS: some flavor of UNIX (Solaris, IRIX, Linux, BSD), Mac OS X or MS windows (with or without cygwin).

The system (binaries, configuration, etc.) needs about 50 MB of disk space (the actual space is platform dependent). To compile GRASS you need around 500 MB of disk space.

Real requirements depend on the data you want to process.

Live CD/DVD are usually more demanding in terms of memory.



# Which data can GRASS r/w?

Like most of the GISs, GRASS uses the GDAL library to handle data file I/O, so basically all the currently used formats are supported.

See <http://www.gdal.org/> for details.

Datum and projection management is done by the PROJ4 library, see <http://proj.maptools.org/>



# How does GRASS run?

GRASS itself is a working environment, the job is actually carried out by programs (called “modules”) running inside this environment.

Currently more than 350 modules are available.

To perform complex tasks modules are combined, each one doing part of the job, usually in scripts.

Moreover, more than 100 add-on modules are available on the GRASS web site.



# How can I find a module?

Modules are grouped by their scope, using significant names *x.action*, where *x* is:

- d.\* - display commands for graphical screen output (ex. d.rast)
- g.\* - general file management commands (ex. g.region)
- i.\* - image processing commands (ex. i.orthophoto)
- r.\* - raster processing commands (ex. r.report)
- r3.\* - raster 3D processing commands (ex. r3.mapcalc)
- v.\* - vector processing commands (ex. v.buffer)
- m.\* - miscellaneous commands
- p.\* / ps.\* - map creation commands (ex. ps.map)
- ... - unix scripts



# What are GRASS projects?

In GRASS projects are broken into three levels:

- **dbase**: the “(geo)database”, basically a directory containing all the data;
- **location**: a set of maps and data *sharing the same datum*;
- **mapset**: a location's subset.

To start a new GRASS project a new location (in this way reference system and projection are set) and a mapset are created.

A *PERMANENT* mapset is created by default to store the datum information and the read-only data (incl. maps).



# What is the *region*?

The *current region* or simply the *region* is a fundamental concept in GRASS: it identifies **the extents and the resolution** (for raster maps) **used in all the operations**, *regardless of the properties of the maps involved*.

All the raster maps are re-sampled on the fly to the resolution of the current region and only the part inside the current region's extents is used (smaller maps are padded with NULL values). However, only output maps are affected from the current region settings, input maps are not modified.

To further complicate the matter, map display is independent from the current region settings.



# How is GRASS used?

There are different ways to use GRASS, depending on your skills and applications' complexity:

- using one of the GUIs - easier to start with, more intuitive;
- using the CLI - more difficult but faster once you know the modules' parameters (and you can reuse the commands);
- using scripts - the best way to use GRASS for experienced users, especially for complex applications; it is possible to automatically rerun the whole procedure after modifying one or more parameters and to use loops, conditional commands execution, ...



# Where can I find more?

This is a GRASS beginners' workshop, extensive documentation exists for the use of GRASS in particular fields.

For example, for GRASS and DBMS see the FOSS4G2007 "GRASS GIS and RDBMS" workshop, or tutorial "Working with GRASS-GIS Vectors and Databases" by Richard Chirgwin in this conference.


A rich source of information is the "Special topic" section of the documentation site:

<http://grass.osgeo.org/gdp/special.php>





Let's start the hands-on part:

- open the tutorial by clicking the Tutorial icon;
- when the tutorial suggests you to do so, run GRASS by clicking on the  icon;
- the dataset is in the “grass” directory and the relevant GRASS' parameter are already set;
- enjoy GRASS!

